

Einführung in die Computerlinguistik

Hidden Markov Models (HMMs)

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Die Grundfassung dieses Foliensatzes wurde von Prof. Dr. Hinrich Schütze erstellt, basiert auf:

Chris Manning and Hinrich Schütze, Foundations of Statistical Natural Language Processing, MIT Press. Cambridge, MA: May 1999.

<https://nlp.stanford.edu/fsnlp/>

Fehler und Mängel sind ausschließlich meine Verantwortung.

- 1 StatNLP
- 2 Basics
- 3 POS tagging
- 4 POS setup
- 5 Probabilistic POS tagging
- 6 Viterbi

Outline

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Statistical Natural Language Processing

Definition

Statistical Natural Language Processing (StatNLP) uses methods of supervised, semisupervised and unsupervised learning to address tasks that involve written or spoken (human) language.

What does “statistical” mean?

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Adjective for “statistics”

statistics = the practice or science of collecting and analyzing numerical data

statistics vs. machine learning

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Statistical parameter estimation

an important / the most important subfield of machine learning

statistics vs. machine learning

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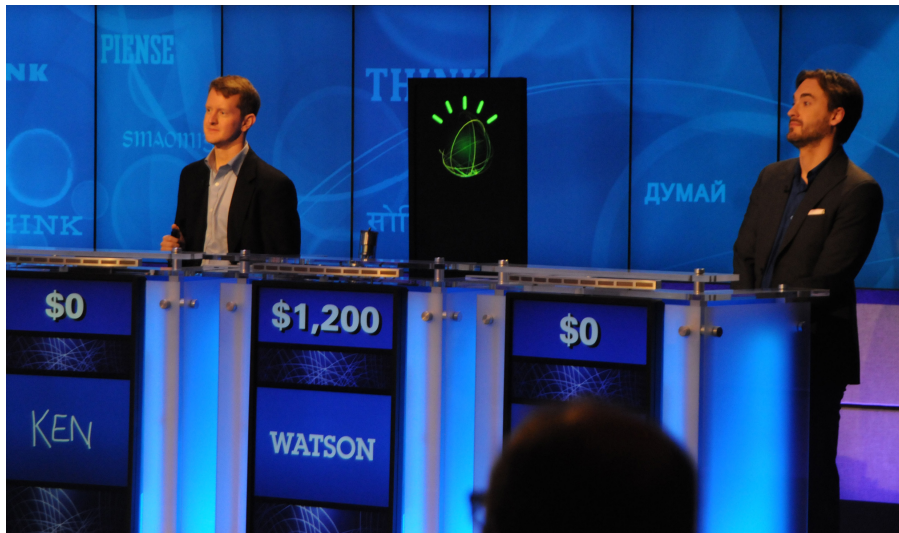
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 - a small group of researchers that do active research on machine learning methods

Recent big success story 1

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Recent big success story 2

Recent big success story 2



Siri. Beta

Your wish is
its command.

Siri on iPhone 4S lets you use your voice to send messages, schedule meetings, place phone calls, and more. Ask Siri to do things just by talking the way you talk. Siri understands what you say, knows what you mean, and even talks back. Siri is so easy to use and does so much, you'll keep finding more and more ways to use it.



Recent big success story 3

Google Translate – more on this later

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max, argmax

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Positive factor $c > 0$ does not affect argmax

$$\operatorname{argmax}_x f(x) = \operatorname{argmax}_x c \cdot f(x)$$

$$\operatorname{argmax}_x f(x) = \operatorname{argmax}_x 1/c \cdot f(x)$$



$$\sum_{i=m}^{i=n} f(i) = f(m) + f(m+1) + \dots + f(n-1) + f(n)$$

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Probability

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- From Axiom 2, it is obvious that $P(A) + P(\bar{A}) = 1$

Joint probability

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- Kolmogorov Axiom 3:
 - 3 If A and B are mutually exclusive (same as $P(AB) = 0$) then the probability of A or B occurring is $P(A) + P(B)$

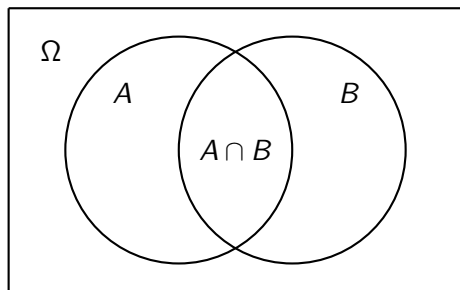
Conditional probability

- The conditional probability is the **updated probability** of an event given some knowledge.

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- Definition: $P(A|B) = \frac{P(AB)}{P(B)}$ ($P(B) > 0$)

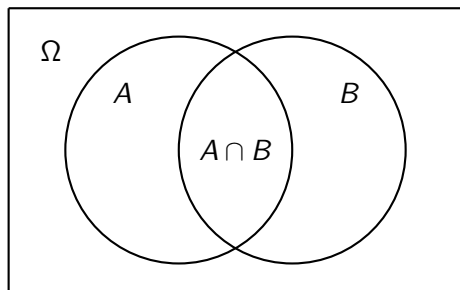
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To compute $P(A|B)$: Divide the area of $A \cap B$ by the area of B .

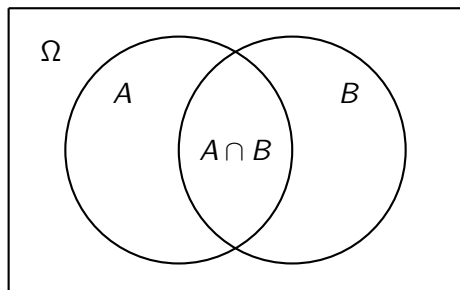
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$$P(A|B) = P(A \cap B) / P(B)$$

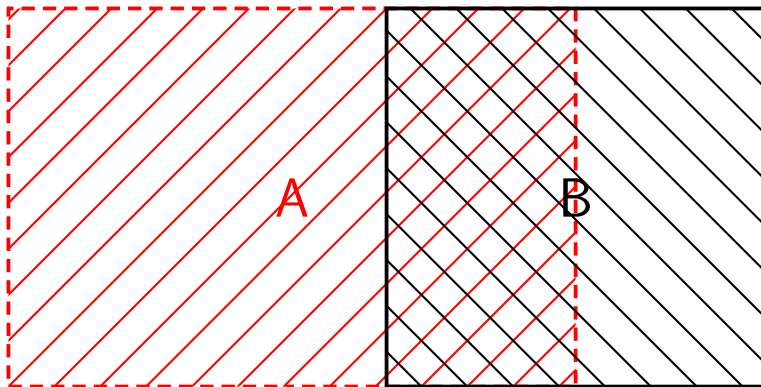
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$$P(X_1 X_2 X_3 \dots X_n) =$$

$$P(X_1) \cdot P(X_2|X_1) \cdot P(X_3|X_1 X_2) \cdot \dots \cdot P(X_n|X_1 X_2 \dots X_{n-1})$$

Bayes' theorem

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- Follows from
$$P(A) = P(AB) + P(A\bar{B}) = P(A|B)P(B) + P(A|\bar{B})P(\bar{B})$$

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- If I learn that A is true, then that doesn't change my assessment of the probability of B (and vice versa).
- If A and B are independent, then:
 $P(A) = P(A|B)$, $P(B) = P(B|A)$

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- Why \approx ?

Testing for independence: Example

A = champagne, B = sparkling

Übung

Find either two independent words or two words that occur less often on the same page than expected by chance

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- In the context “the book” it can only be a noun.
- In the context “to book a flight” it can only be a verb.
- Part-of-speech tagging assigns to “book” the correct syntactic category in context.

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- Are all cases of part-of-speech tagging this easy?

Hard example

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The following sentence is ambiguous wrt POS. Why?

The representative put chairs on the table

AT	NN	VBD	NNS	IN	AT	NN
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AT JJ NN VBZ IN AT NN
article adjective noun verb-z prep article noun

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In this case, finding the correct parts of speech for the sentence is more difficult.

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- Part-of-speech tagging is used as a [preprocessing step](#).
- It is solvable: Very high accuracy rates can be achieved (95–98% for English).
- It helps with many things you want to do with text, e.g., chunking, information extraction, question answering and parsing.

Part-of-speech tagging of tweets

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ikr	smh	he	asked	fir	yo	last
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name	so	he	can	add	u	on
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Example from: Owoputi et al. (2012). Part-of-Speech Tagging for Twitter: Word Clusters and Other Advances. Tech Report. See <http://www.cs.cmu.edu/~ark/TweetNLP/>

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IN	preposition	TO	the word “to”
JJ	adjective	VB	verb, base form
JJR	comparative adjective	VBD	verb, past tense
MD	modal	VBG	verb, present participle, gerund
NN	singular or mass noun	VBN	verb, past participle
NNP	singular proper noun	VBZ	verb, 3rd singular present
NNS	plural noun	WDT	wh-determiner: “what”, “which”, ...
PERIOD	. : ? !		
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Tag: “Peter arrived in London on Tuesday”

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The following sentence is ambiguous wrt POS. Why?

The	representative	put	chairs	on	the	table
AT	NN	VBD	NNS	IN	AT	NN
article	noun	verb-d	noun-s	prep	article	noun
AT	JJ	NN	VBZ	IN	AT	NN
article	adjective	noun	verb-z	prep	article	noun

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 - Example: for a JJ/NN ambiguity in the context “AT _ VBZ”, NN is much more likely than JJ.
- 2 A word's **bias** for the different parts of speech
 - Example: “put” is much more likely to occur as a VBD than as an NN.

Information sources

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- This source of information lets us do 90% correct tagging of English very easily: Just pick the most frequent tag for each word.
- For most words in English, the distribution of tags is very **uneven**: there is one very frequent tag and the others are rare.

Notation

Notation

w_i	the word at position i in the corpus
t_i	the tag of w_i
w^l	the l^{th} word in the lexicon
t^j	the j^{th} tag in the tag set
$C(w^l)$	the number of occurrences of w^l in the training set
$C(t^j)$	the number of occurrences of t^j in the training set
$C(t^j t^k)$	the number of occurrences of t^j followed by t^k
$C(w^l : t^j)$	the number of occurrences of w^l that are tagged as t^j

Notation: Example

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the	representative	put	chairs	on	the	table
w_1	w_2	w_3	w_4	w_5	w_6	w_7
w^5	w^{81}	w^3	w^4	w^1	w^5	w^6
AT	NN	VBD	NNS	IN	AT	NN
article	noun	verb-d	noun-s	prep	article	noun
t_1	t_2	t_3	t_4	t_5	t_6	t_7
t^{16}	t^{12}	t^2	t^9	t^3	t^{16}	t^{12}

$$\begin{array}{l}
 C(w^5) = 2 \\
 C(t^{16}) = 2 \\
 C(t^{16}t^{12}) = 2 \\
 C(t^{16}t^2) = 0 \\
 C(w^5 : t^{16}) = 2
 \end{array}
 \left|
 \begin{array}{l}
 C(w^4) = 1 \\
 C(t^2) = 1 \\
 C(t^{12}t^2) = 1 \\
 C(w^5w^{81}) = 1 \\
 C(w^5 : t^{12}) = 0
 \end{array}
 \right.$$

Confidence/**NN** in/**IN** the/**AT** pound/**NN** is/**BEZ** widely/**RB**
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Give the values of the following: w_4 , t_5 , $C(w_8)$, $C(t_9)$, $C(t_1 t_2)$,
 $C(w_3 : t_3)$

Supervised learning

- **Labeled training set:** each word is annotated (or marked or tagged) by a linguist, with correct part-of-speech

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- **Labeled training set:** each word is annotated (or marked or tagged) by a linguist, with correct part-of-speech
- **Train** a statistical model on the training set
 - Result: A set of parameters (= numbers) that were learned from the specific properties of the training set
- Apply statistical model to new text that we want to analyze for some task (information retrieval, machine translation etc)

Tagged training corpus/set: Example

Confidence/NN in/IN the/AT pound/NN is/BEZ widely/RB
expected/VBN to/TO take/VB another/AT sharp/JJ dive/NN
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a/AT substantial/JJ improvement/NN from/IN July/NNP and/CC
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Outline

- 1 StatNLP
- 2 Basics
- 3 POS tagging
- 4 POS setup
- 5 Probabilistic POS tagging**
- 6 Viterbi

Contents of this section

- Parameter estimation: context parameters
- Parameter estimation: bias parameters
- Greedy tagging
- Viterbi tagging

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- This will be our formalization of the first source of information in tagging: the context.
- Note that this is a very impoverished model of context.
 - Limited horizon, Markov assumption: we assume that our memory is limited to a [single preceding tag](#).
 - Time invariance, stationary: we assume that these conditional probabilities don't change. (e.g., the same at the beginning and at the end of the sentence)

Parameter estimation: Context

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- Training text: long tagged sequence of words

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$$\hat{P}_{ml}(t^k|t^j) = \frac{\hat{P}_{ml}(t^j t^k)}{\hat{P}_{ml}(t^j)} \approx \frac{\frac{C(t^j t^k)}{C(\cdot)}}{\frac{C(t^j)}{C(\cdot)}} = \frac{C(t^j t^k)}{C(t^j)}$$

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$$\hat{P}_{ml}(\text{NN}|\text{JJ}) = \frac{C(\text{JJ NN})}{C(\text{JJ})}$$

In an n^{th} order Markov model,
the tag at time t depends on the n previous tags.

- Order 0: Tag does not depend on previous tags.
- Order 1: Tag depends on immediately preceding tag.
- Order 2: Tag depends on two immediately preceding tags.
- Order 3: Tag depends on three immediately preceding tags.
- ...

(analogous for Markov model that emits words instead of tags)

Parameter estimation: Word bias

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- How to estimate $P(\text{book}|\text{NN})$

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-

$$\hat{P}_{ml}(w^l|t^j) = \frac{\hat{P}_{ml}(w^l : t^j)}{\hat{P}_{ml}(t^j)} = \frac{\frac{C(w^l:t^j)}{C(.)}}{\frac{C(t^j)}{C(.)}} = \frac{C(w^l : t^j)}{C(t^j)}$$

- How to estimate $P(\text{book}|\text{NN})$



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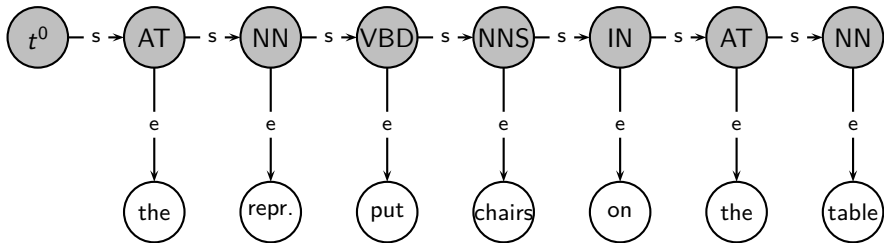
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Estimate $P(\text{take}|\text{VB})$ and $P(\text{AT}|\text{IN})$

- What about the second source of information: frequency of different tags for a word?
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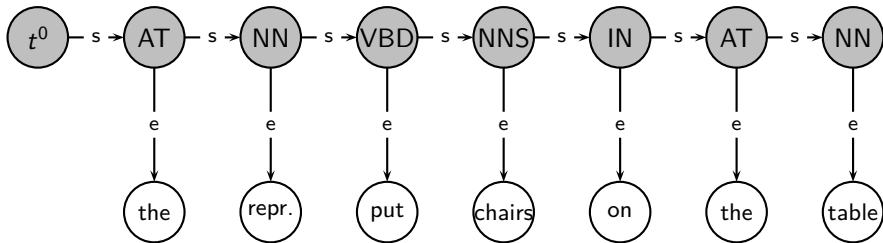
$P(w|t)$ versus $P(t|w)$

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 - Output: AT NN VBD NNS IN AT NN
- At decoding time, our task is to recover the tags (= states). This model is called a “Hidden Markov Model” because we don’t know the states.

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- How can we do this?

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- $t_3 = \text{VBD}$ maximizes $P(t_3|\text{NN})P(\text{put}|t_3)$

Problems with greedy tagging

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- What can go wrong with greedy tagging?

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Problems with greedy tagging

- What can go wrong with greedy tagging?
- Example?
- The representative put costs 20% more today than a month ago.

Notation (2)

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w_i	the word at position i in the corpus
t_i	the tag of w_i
$w_{i,i+m}$	the words occurring at positions i through $i + m$ (alternative notations: $w_i \cdots w_{i+m}$, w_i, \dots, w_{i+m} , $w_{i(i+m)}$)
$t_{i,i+m}$	the tags $t_i \cdots t_{i+m}$ for $w_i \cdots w_{i+m}$
w^l	the l^{th} word in the lexicon
t^j	the j^{th} tag in the tag set
$C(w^l)$	the number of occurrences of w^l in the training set
$C(t^j)$	the number of occurrences of t^j in the training set
$C(t^j t^k)$	the number of occurrences of t^j followed by t^k
$C(w^l : t^j)$	the number of occurrences of w^l that are tagged as t^j
T	number of tags in tag set
W	number of words in the lexicon
n	sentence length

Part-of-speech tagging: Problem statement

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Part-of-speech tagging: Problem statement

- We define our goal thus: Given a sentence, find the most probable sequence of tags for this sentence.
- Formalization of this goal:

$$t_{1,n} = \operatorname{argmax}_{t_{1,n}} P(t_{1,n} | w_{1,n})$$

Simplifying the argmax (1)

$$t_{1,n} = \operatorname{argmax}_{t_{1,n}} P(t_{1,n} | w_{1,n}) \quad (1)$$

$$= \operatorname{argmax}_{t_{1,n}} P(t_{0,n} | w_{1,n}) \quad (2)$$

$$= \operatorname{argmax}_{t_{1,n}} \frac{P(w_{1,n} | t_{0,n}) P(t_{0,n})}{P(w_{1,n})} \quad (3)$$

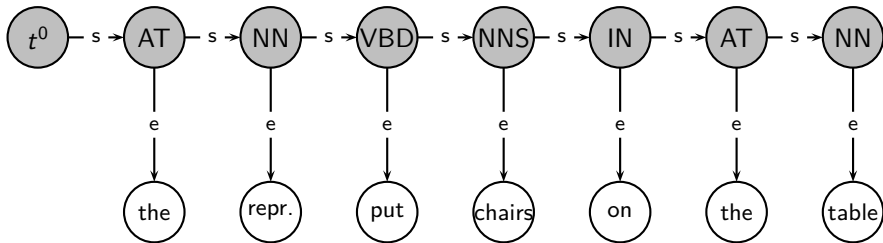
$$= \operatorname{argmax}_{t_{1,n}} P(w_{1,n} | t_{0,n}) P(t_{0,n}) \quad (4)$$

$$= \operatorname{argmax}_{t_{1,n}} \left[\prod_{i=1}^n P(w_i | t_{0,n}) \right] P(t_{0,n}) \quad (5)$$

2: dummy “start” tag; 3: Bayes; 4: positive factor doesn’t affect argmax; 5: assumption: words are independent

$P(w|t)$ versus $P(t|w)$

(s = sequence, e = emission)



- This is a so-called “generative model”.
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Simplifying the argmax (2)

$$= \operatorname{argmax}_{t_{1,n}} \left[\prod_{i=1}^n P(w_i | t_i) \right] P(t_{0,n}) \quad (6)$$

$$= \operatorname{argmax}_{t_{1,n}} \left[\prod_{i=1}^n P(w_i | t_i) \right] \left[\prod_{i=1}^n P(t_i | t_{0,i-1}) \right] \quad (7)$$

$$= \operatorname{argmax}_{t_{1,n}} \left[\prod_{i=1}^n P(w_i | t_i) \right] \left[\prod_{i=1}^n P(t_i | t_{i-1}) \right] \quad (8)$$

$$= \operatorname{argmax}_{t_{1,n}} \prod_{i=1}^n [P(w_i | t_i) P(t_i | t_{i-1})] \quad (9)$$

7: chain rule; 8: Markov assumption; 9:

$$\prod_{i=1}^n x_i \prod_{i=1}^n y_i = \prod_{i=1}^n x_i y_i$$

Simplifying the argmax (3)

$$= \operatorname{argmax}_{t_{1,n}} \prod_{i=1}^n [P(w_i|t_i)P(t_i|t_{i-1})] \quad (10)$$

$$= \operatorname{argmax}_{t_{1,n}} \sum_{i=1}^n [\log P(w_i|t_i) + \log P(t_i|t_{i-1})] \quad (11)$$

11: computation in log space more efficient / convenient

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The most probable tag sequence (= tagging)

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What's the difficulty if you want to tag based on this?

Brute force is very inefficient

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$40^{20} = 109,951,162,777,600,000,000,000,000,000$

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Is there a better way?

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- Overlapping subsolutions: The best path that gets me to tag t at position j is needed for computing all T paths at position $j + 1$...
- ...but I only compute it once!

$$P(t_i | t_{i-1})$$

Example: $P(\text{VB} | \text{MD}) = 0.7968$

	NNP	MD	VB	JJ	NN	RB	DT
<s>	0.2767	0.0006	0.0031	0.0453	0.0449	0.0510	0.2026
NNP	0.3777	0.0110	0.0009	0.0084	0.0584	0.0090	0.0025
MD	0.0008	0.0002	0.7968	0.0005	0.0008	0.1698	0.0041
VB	0.0322	0.0005	0.0050	0.0837	0.0615	0.0514	0.2231
JJ	0.0366	0.0004	0.0001	0.0733	0.4509	0.0036	0.0036
NN	0.0096	0.0176	0.0014	0.0086	0.1216	0.0177	0.0068
RB	0.0068	0.0102	0.1011	0.1012	0.0120	0.0728	0.0479
DT	0.1147	0.0021	0.0002	0.2157	0.4744	0.0102	0.0017

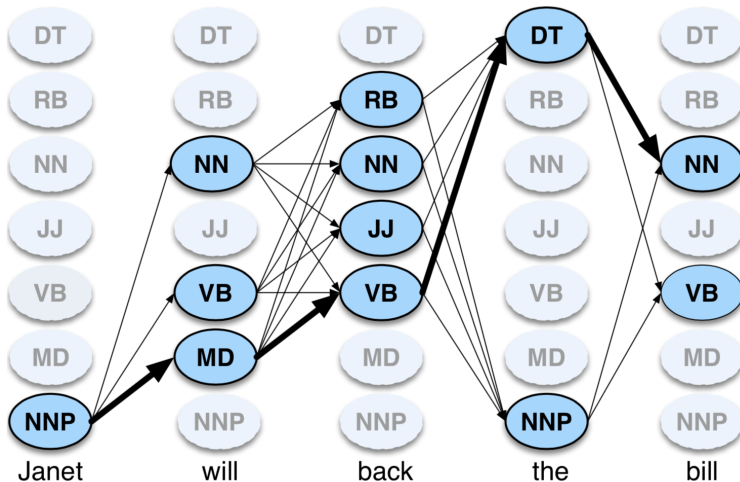
vertical axis: t_{i-1}

horizontal axis: t_i

$P(w|t)$ Example: $P(\text{the}|\text{DT}) = 0.506099$

	Janet	will	back	the	bill
NNP	0.000032	0	0	0.000048	0
MD	0	0.308431	0	0	0
VB	0	0.000028	0.000672	0	0.000028
JJ	0	0	0.000340	0	0
NN	0	0.000200	0.000223	0	0.002337
RB	0	0	0.010446	0	0
DT	0	0	0	0.506099	0

Key idea of Viterbi: Lattice



function VITERBI(*observations* of len T , *state-graph* of len N) **returns** *best-path*, *path-prob*

create a path probability matrix *viterbi*[N , T]

for each state s **from** 1 **to** N **do** ; initialization step

$viterbi[s,1] \leftarrow \pi_s * b_s(o_1)$

$backpointer[s,1] \leftarrow 0$

for each time step t **from** 2 **to** T **do** ; recursion step

for each state s **from** 1 **to** N **do**

$viterbi[s,t] \leftarrow \max_{s'=1}^N viterbi[s',t-1] * a_{s',s} * b_s(o_t)$

$backpointer[s,t] \leftarrow \operatorname{argmax}_{s'=1}^N viterbi[s',t-1] * a_{s',s} * b_s(o_t)$

$bestpathprob \leftarrow \max_{s=1}^N viterbi[s,T]$; termination step

$bestpathpointer \leftarrow \operatorname{argmax}_{s=1}^N viterbi[s,T]$; termination step

$bestpath \leftarrow$ the path starting at state $bestpathpointer$, that follows $backpointer[]$ to states back in time

return $bestpath$, $bestpathprob$

$$P(t_i | t_{i-1})$$

Example: $P(\text{VB} | \text{NN}) = 0.5$

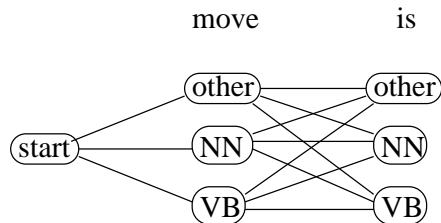
prev	next	other	NN	VB
start		0.3	0.4	0.3
other		0.2	0.2	0.6
NN		0.4	0.1	0.5
VB		0.1	0.8	0.1

vertical axis: t_{i-1}

horizontal axis: t_i

$P(w|t)$ Example: $P(\text{bear}|\text{NN}) = 0.45$

	other	NN	VB
bear	0.1	0.45	0.4
is	0.3	0.05	0.05
on	0.3	0.05	0.05
the	0.2	0.05	0.05
move	0.1	0.4	0.45



Goal: Compute

$$\arg \max_{t_1, t_2} p(t_1, \text{move}, t_2, \text{is}) =$$

$$\arg \max_{t_1, t_2} p(t_1 | \text{start}) p(\text{move} | t_1) p(t_2 | t_1) p(\text{is} | t_2)$$

viterbi = vtrb

backpointer = bptr

lattice = path probability matrix

$vtrb_j(t_i)$ is the probability of [the most probable path from 0 to j that tags word w_j with tag t_i].

$bptr_j(t_i)$ is the tag of w_{j-1} on [the most probable path from 0 to j that tags word w_j with tag t_i].

Initialization: $vtrb_0(start) = 1$

Viterbi probabilities for the tags of the first word

$$\text{vtrb}_1(\text{other}) = \text{vtrb}_0(\text{start}) p(\text{other}|\text{start}) p(\text{move}|\text{other}) = 1.0 * 0.3 * 0.1 = 0.03$$

$$\text{vtrb}_1(\text{NN}) = \text{vtrb}_0(\text{start}) p(\text{NN}|\text{start}) p(\text{move}|\text{NN}) = 1.0 * 0.4 * 0.4 = 0.16$$

$$\text{vtrb}_1(\text{VB}) = \text{vtrb}_0(\text{start}) p(\text{VB}|\text{start}) p(\text{move}|\text{VB}) = 1.0 * 0.3 * 0.45 = 0.135$$

Viterbi probabilities for the tags of the second word (1)

$$\begin{aligned} \text{vtrb}_2(\text{other}) = \max(\\ & \text{vtrb}_1(\text{other}) p(\text{other}|\text{other}) p(\text{is}|\text{other}) = 0.03 * 0.2 * 0.3 = 0.0018, \\ & \text{vtrb}_1(\text{NN}) p(\text{other}|\text{NN}) p(\text{is}|\text{other}) = 0.16 * 0.4 * 0.3 = 0.0192, \\ & \text{vtrb}_1(\text{VB}) p(\text{other}|\text{VB}) p(\text{is}|\text{other}) = 0.135 * 0.1 * 0.3 = 0.00405 \\) = 0.0192 \\ \text{bptr}_2(\text{other}) = \text{NN} \end{aligned}$$

Viterbi probabilities for the tags of the second word (2)

$$\begin{aligned} \text{vtrb}_2(\text{NN}) = \max(& \\ & \text{vtrb}_1(\text{other}) p(\text{NN}|\text{other}) p(\text{is}|\text{NN}) = 0.03 * 0.2 * 0.05 = 0.0003, \\ & \text{vtrb}_1(\text{NN}) p(\text{NN}|\text{NN}) p(\text{is}|\text{NN}) = 0.16 * 0.1 * 0.05 = 0.0008, \\ & \text{vtrb}_1(\text{VB}) p(\text{NN}|\text{VB}) p(\text{is}|\text{NN}) = 0.135 * 0.8 * 0.05 = 0.0054 \\ &) = 0.0054 \\ & \text{bptr}_2(\text{NN}) = \text{VB} \end{aligned}$$

Viterbi probabilities for the tags of the second word (3)

$$\begin{aligned} \text{vtrb}_2(\text{VB}) = \max(\\ & \text{vtrb}_1(\text{other}) p(\text{VB}|\text{other}) p(\text{is}|\text{VB}) = 0.03 * 0.6 * 0.05 = 0.0009, \\ & \text{vtrb}_1(\text{NN}) p(\text{VB}|\text{NN}) p(\text{is}|\text{VB}) = 0.16 * 0.5 * 0.05 = 0.004, \\ & \text{vtrb}_1(\text{VB}) p(\text{VB}|\text{VB}) p(\text{is}|\text{VB}) = 0.135 * 0.1 * 0.05 = 0.000675 \\) = 0.004 \\ \text{bptr}_2(\text{VB}) = \text{NN} \end{aligned}$$

Probability of the most likely path: $0.0192 = \max_t vtrb_2(t)$

Last tag of the most likely path: $other = \arg \max_t vtrb_2(t)$

First tag of the most likely path: $NN = bptr_2(other)$

Result:

$NN \ other = \arg \max_{t_1 t_2} p(t_1, \text{move}, t_2, \text{is})$

- Part-of-speech tagging, informal definition
- Part-of-speech tagging, formal definition

$$\operatorname{argmax}_{t_{1,n}} \sum_{i=1}^n [\log P(w_i | t_i) + \log P(t_i | t_{i-1})]$$

- Brown part-of-speech tags
- Parameter estimation: Context

$$\hat{P}(t^k | t^j) = \frac{C(t^j t^k)}{C(t^j)}$$

- Parameter estimation: Word bias

$$\hat{P}(w^l | t^j) = \frac{C(w^l : t^j)}{C(t^j)}$$

- Order of a Markov model
- Viterbi