Transformer and Unsupervised NMT

Erweiterungsmodul: Machine Translation Sommersemester 2020

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June 9, 2020

Outline

- Transformer
 - Self-attention
 - Transformer building blocks
- Document-Level Neural Machine Translation
 - Discourse-level phenomena
 - Models
- Unsupervised Neural Machine Translation
 - Initialization
 - Denoising auto-encoding
 - Iterative backtranslation
 - Combining the techniques

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A Brief History

- Machine translation: the task of receiving a sentence in the source language and outputting a translation in the target language
- RNN encoder-decoder proved that this is possible with neural networks (Sutskever, Vinyals, and Le 2014)
- Attention-based encoder-decoder provided state-of-the-art performance (Bahdanau, Cho, and Bengio 2015)
- Convolutional encoder-decoder (Gehring et al. 2017)
- Transformer Attention is all you need (Vaswani et al. 2017)

Why Not RNN Encoder-Decoder

- Up to Transformer, most models implemented with attention-based RNN encoder-decoder
- RNNs process words sequentially
- They do not lend themselves to parallelization
- Difficult to model long-term dependencies

Modeling Long-Term Dependencies

- Bidirectional RNN enable more meaningful modeling of words near the end
- Attention enables direct access to all hidden states
- Still not a fundamental solution to the problem, the interplay between hidden states of arbitrary words is limited

Parallelization

- Very important in the big data era
- Robust MT requires milions of parallel sentences
- Convolutional encoder-decoder help with parallelization, but require many layers to be able to model long-term dependencies

Transformer

- First purely self-attention-based encoder-decoder model all hidden states interact with each other
- Can easily be parallelized
- State-of-the-art model architecture for MT and most NLP tasks
- Used for training large Language Models (BERT, GPT-2) which provide large improvements in many NLP tasks by making use of transfer learning

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Attention in RNN Encoder-Decoder

- Hidden states computed with an RNN
- Attention computed at each decoder step
- Attention over encoder hidden states
- Computed "context" vector integrated into decoder hidden state

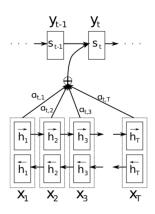


Figure from Bahdanau, Cho, and Bengio 2015

Attention in RNN Encoder-Decoder

- Motivation: do not summarize the whole sentence in a single vector
- Variable length representation keep RNN hidden states for each word
- Pay more attention to more relevant hidden states (words)
- Attention determines what source words are important for predicting the next target word

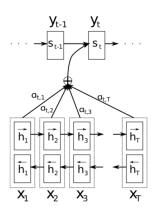
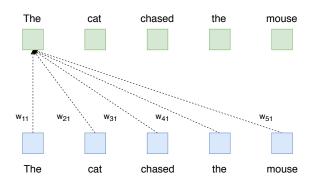
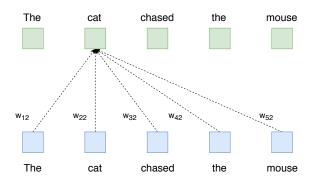
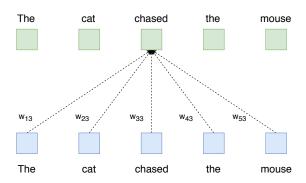


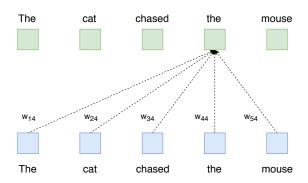
Figure from Bahdanau, Cho, and Bengio 2015

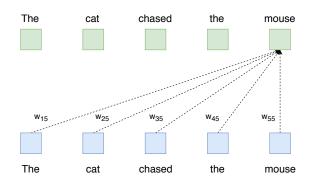
- Also intra-attention relating different positions of the same input sequence
- All hidden states are computed using only attention
 - No recurrence all recurrent connections replaced with attention
 - Self-attention replaces the RNN
- A given hidden state is a weighted linear combination of all hidden states
 - A given word interacts with all other words, including itself











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Attention

Queries Q, Keys K, Values V

The interaction between Q and K determines how to score V (how important certain values are).

In Bahdanau, Cho, and Bengio 2015, $\it Q$ is the current decoder state, $\it K$ and $\it V$ are all encoder states.

Computing Attention

Bahdanau, Cho, and Bengio 2015 used multi-layer perceptron for the attention

$$\begin{aligned} c_j &= \sum_{i}^{T_x} \alpha_{ij} h_i \\ \alpha_{ij} &= \frac{\exp(e_{ij})}{\sum_{k=1}^{T_X} \exp(e_{kj})} \\ e_{ij} &= v_a^\mathsf{T} \tanh \left(U_a s_j' + W_a h_i \right) \end{aligned}$$

But it requires additional parameters U_a , W_a and v_a s_j - decoder hidden state, h_i - encoder hidden state

Scaled Dot-Product Attention

Dot-product attention does not require parameters

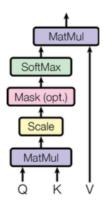
$$a(q,k) = qk^T$$

Dimensionality of q and k has to be the same.

The scale of the dot product depends on the dimensionality of the vectors. Scale grows as dimensionality grows. Can be fixed by scaling proportionally to the dimensionality:

$$a(q,k) = \frac{qk^T}{\sqrt{|k|}}$$

Scaled Dot-Product Attention in Transformer



$$Attention(Q, K, V) = softmax(\frac{QK^T}{\sqrt{d_K}})V$$

Vaswani et al. 2017

Queries, Keys and Values in Self-Attention

- for self-attention, the input is Q, K and V at the same time
- At Transformer encoder layer 1 (E is token embedding)
- In practice, the Transformer learns 3 separate projection layers at each encoder or decoder layer for Q, K and V.

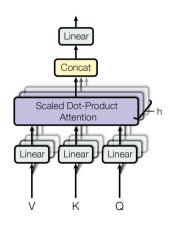
$$Q = EW_1^Q, K = EW_1^K, V = EW_1^V$$

Multi-Head Attention

- Computing one attention may be too brittle
- Separation of concerns learn multiple separate attentions.
- Intuition is that different attention heads learn different things and are allowed to focus on different things in the input
- Conceptually, one head may learn to incorporate local information for each token representation and another may learn to look for potential long-term dependencies
- Many works try to interpret attention, but it is not clear if strong conclusions can be made by looking at attention scores

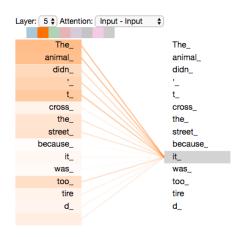
Multi-Head Attention in Transformer

- Transformer learns h attention heads (initially 8, but lots of other values have been tried)
- Linear projection layers W project the input to dimensionality d/h. Separate linear layers for each head.
- Output of all attention heads is later concatenated and an additional linear layer is applied
- Computational overhead of multiple attention heads compensated by applying attention over smaller parameters spaces



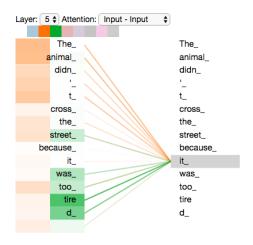
Vaswani et al 2017

Multi-Head Attention - Visualizations



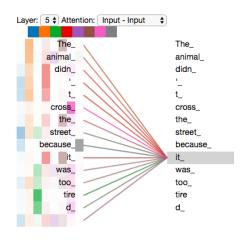
http://jalammar.github.io/illustrated-transformer/

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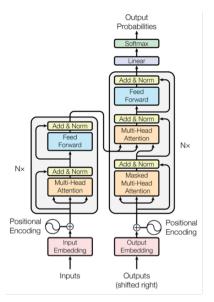
http://jalammar.github.io/illustrated-transformer/

Positional Information

- Positional information is built-in in RNN encoder-decoder by way of processing the input sequentially
- Self-attention is ignorant of any positional information and therefore has to be explicitly provided
- Learns separate embeddings for positional information maximum length has to be specified
- Transformer introduced sinusoidal positional embeddings may allow for easier learning of relative position information and extrapolation to unseen sequence lengths

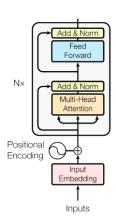
Transformer

- Multiple encoder and decoder layers
- Token-level and positional embeddings
- Multi-head attention
 - Self-Attention
 - Encoder attention
- Feed-forward networks
- Residual connections (Add)
- Layer normalization (Norm)
- Final linear projection to size of vocabulary and softmax to determine most probable next output token



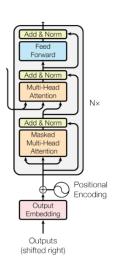
Transformer Encoder

- Apply multi-head self-attention to input as we talked about before
- Residual connection, add the input to multi-head attention to its output
- Apply layer normalization
- Apply a feed-forward neural network
- Residual connection + layer normalization



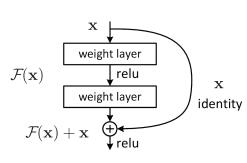
Transformer Decoder

- Masked multi-head self-attention
- Attention over encoder hidden states
- Remaining components used as before



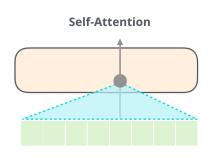
Residual Connections, Layer Norm, Position-wise Feed-Forward NN

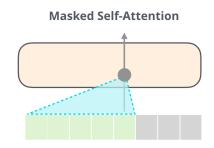
- Deep neural networks can be difficult to train - gradients may explode or vanish
- Residual connections and layer normalization address these issues
- Feed-forward neural network is applied to each position separately and identically



He et al 2016

Masking





 $\verb|http://jalammar.github.io/illustrated-gpt2/|$

Comparison to RNN and Convolution

Layer Type	Complexity per Layer	Sequential Operations	Maximum Path Length
Self-Attention	$O(n^2 \cdot d)$	O(1)	O(1)
Recurrent	$O(n \cdot d^2)$	O(n)	O(n)
Convolutional	$O(\hat{k}\cdot n\cdot \hat{d}^2)$	O(1)	$O(log_k(n))$
Self-Attention (restricted)	$O(r \cdot n \cdot d)$	O(1)	O(n/r)

- n sequence length, d representation dimension, k kernel size of convolutions
- Sequential operations how much can be parallelized
- Maximum Path Length: path length between long-range dependencies

Conclusion

- Self-attention a powerful mechanism
- Multi-head attention
- Parallelizable, instant access to all inputs, less complexity
- Transformers are ubiquitous in NMT and NLP

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Document-Level Machine Translation

- Traditionally MT works on the sentence-level single sentence input and output
- Phrase-based and Neural MT are both largely ignorant of broader discourse-level phenomena

Why do we do sentence-level NMT?

- Resource limitations memory requirements
- Document-level models may be challenging to train
- Document-aligned data is scarce
- A high portion of publicly available datasets either do not preserve the sequential order or lack document boundaries
- Why is this the case? most of textual data is part of some document in one form or another
- Likely because of historical reasons small number of works on document-level MT

Claims of human parity

- Some works have claimed that they have achieved human parity in MT Hassan et al. 2018
- These claims have been challenged by L\u00e4ubli, Sennrich, and Volk 2018; Toral et al. 2018
- Among other remarks, both works note that the manual evaluation was done in a context-agnostic way

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Discourse-level phenomena

- Coreference (anaphora) resolution
 - Important for gender and number pronoun agreement
 - It presents a problem. \rightarrow Er [masculine] präsentiert ein Problem.
 - Context: Let me summarize the novel for you.
- Coherence consistency to concepts and world knowledge
- Cohesion consistency to surface formulations
- Deixis words and phrases that cannot be understood without context (time and place dependent), formality
- Style "is anybody hurt" and "is someone wounded"
- Domain important for domain-dependent ambiguous translations

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Document-level NMT

- Also referred to as context-aware NMT
- Using contextual (document) information
- Main questions:
 - How do we process/model the context?
 - How do we integrate contextual information in our models?

Document-level MT

- How do context-aware (document-level) models differ?
- Source-Target
 - Do they use source or target side contextual information?
- Fine-grained vs. coarse-grained
 - Do they aim to obtain a fine-grained or coarse-grained document representation?
- Input-Output
 - Do they only input large pieces of text or do they output them as well?
- Previous-Subsequent context
- Many methods are a mix of different types.

Concatenation models

- First work by Tiedemann and Scherrer 2017
- Concatenate consecutive sentences on the input side
 - And optionally on the output side as well

Input

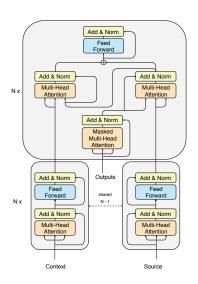
Let me summarize the novel for you. [SEP] It presents a problem.

Output

Ich fasse den Roman für dich zusammen. [SEP] Er präsentiert ein Problem.

- No need to modify the baseline NMT architecture or to come up with a context integration scheme
- Works fine with a limited number of contextual sentences, but some effort is required to scale to an large sized context. Straightforward application to very large sequences almost impossible.

Context-aware Transformer



Stojanovski and Fraser 2019

Context integration

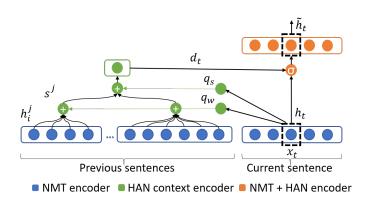
- Gating
- dm_i main sentence representation in decoder (after dec-to-enc attention)
- dc_i context sentence representation in decoder
- Compute a gate z_i
- Control how much contextual information is needed for the prediction of the next word

$$z_i = \sigma(U_z dm_i + W_z dc_i)$$

$$d_i = z_i * dm_i + (1 - z_i) * dc_i$$



Hierarchical attention



 Miculicich et al. 2018 - attention over tokens followed by attention over sentences

Conclusion

- Are context-aware models going to be more widely used by the MT community?
- The potential benefits from contextual information are clear
- Flexible, simple and scalable models
- Transformer LM capable of large input modeling adaptation to NMT?

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Unsupervised Neural Machine Translation

- NMT models require parallel data to be efficiently trained
- Parallel data is scarce across many language pairs and domains
- Monolingual data on the other hand is prevalent
- There are works making use of monolingual data, but still need parallel data as well
- Unsupervised NMT uses monolingual data only

Critical Components of Unsupervised MT

Meaningful initialization:

- random initialization works for models trained on parallel data, but it is useless for UMT
- Unsupervised Bilingual Word Embeddings

Iterative improvement

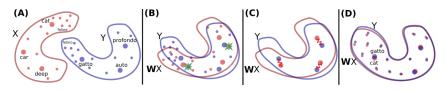
- Denoising auto-encoding
- Iterative backtranslation

Unsupervised NMT - Important Ingredients

- Proper initialization unsupervised BWEs
- Learn to generate proper language
 - Denoising auto-encoding
- Enable continuous improvement
 - Iterative backtranslation
- One model for both translation directions

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Unsupervised Bilingual Word Embeddings



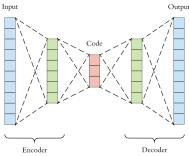
- Works well for closely related languages, less so for distant languages
- Use unsupervised BWEs to initialize the NMT embeddings
- Use the unsupervised BWEs to do bilingual lexicon induction
- Use induced lexicon to create word-by-word translation
 - Not appropriate for: reordering, compound words, phrases

Lample et al. 2018c

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Denoising Auto-Encoding

- How can we make the model generate proper target language sentences?
- Reconstruct the input a trivial task because it only involves copying
- What if we add noise to the input and try to reconstruct the original?



Vincent et al. 2010,

Denoising Auto-Encoding - Noise

• Randomly drop words

X = I am tired because I went on a run Drop(X) = I am because I went on run

Denoising auto-encoding $Drop(X) \rightarrow X$

I am because I went on run \rightarrow I am tired because I went on a run

- a word is dropped with a certain probability p_{wd}
- the model learns important properties about the language
- word insertions: a run
- perhaps something about semantics as well: tired run

Denosing Auto-Encoding - Noise

Permute words within a certain neighborhood

X = I want to play tennis on Friday Shuffle(X) = I want to on Friday tennis play

Denoising auto-encoding $Shuffle(X) \rightarrow X$

I want to on Friday tennis play ightarrow I want to play tennis on Friday

In German Ich möchte am Freitag Tennis spielen

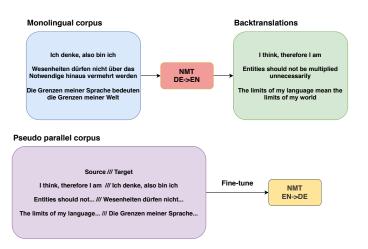
- the model can learn to do word reordering
- important when word order between the 2 languages is not the same, e.g. English and German

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Backtranslation

- Effective way to integrate monolingual data
- Steps:
 - Find target language monolingual data M_t
 - Train a reverse NMT model if we care about English to German translation, we will train an additional German to English model NMT_{de-en}
 - Use the trained reverse model NMT_{de-en} to translate the monolingual data M_t
 - Create a pseudo parallel corpus: pair the corresponding monolingual sentences with the obtained translations
 - Translations on the source side, monolingual data on the target
 - ullet Fine-tune the NMT_{en-de} model with the new pseudo parallel corpus

Backtranslation



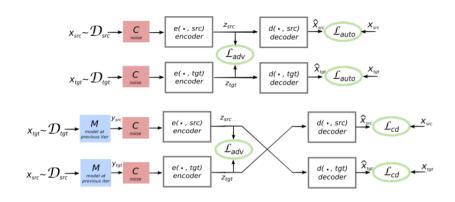
Iterative Backtranslation

- Backtranslation improves performances
 - Translations are noisy encoder learns to deal with noise better
 - Almost arbitrary amount of pseudo parallel data
- But why should we do it only once?
- If the model improves, we can use the improved model to generate new backtranslations and repeat the process - iterative backtranslation
- On-the-fly iterative backtranslation
 - For UNMT, one model can do both translation directions
 - No need to backtranslate the whole corpus before fine-tuning
 - Backtranslate and fine-tune alternately



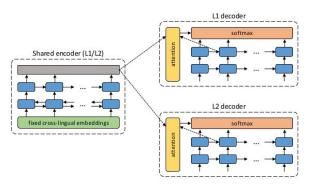
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 - Self-attention
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Putting It All Together



Lample et al. 2018b

Architecture details



- The same model must be used for:
 - L1 \rightarrow L1 and L2 \rightarrow L2 (denoising auto-encoding)
 - L1 \rightarrow L2 and L2 \rightarrow L1 (translation)
- Encoder representation should be language-agnostic
- Lample et al. 2018b use adversarial training

Artetxe et al. 2018

Unsupervised NMT Lample et al. 2018a

- BPE-level model
 - Previously word-level models
- Single unified model
 - Single encoder, single decoder
- No adversarial training

Shared BPEs

- Take L1 and L2 monolingual corpora and split on BPE-level
 - Jointly learn on both languages to enable more frequent BPE sharing
- Train fasttext word embeddings
- Initialize NMT embeddings
- Embeddings are shown to be a useful initialization for UNMT
- Caveat: L1 and L2 need to share surface forms. Works well for English and German, not for English and Nepali.

Unified Model

- Single encoder and decoder (no discriminator or adversarial training)
- How do we deal with encoder language representation?
- Special language tag in decoder <2en>, <2de>
- Encoder has to learn a language-agnostic representation because the same representation can be used for denoising auto-encoding or translation
- Decoder is forced fed the language tag and knows what language to generate

Conclusion

- Most of the basic techniques explained here are still used
- Most works use pretrained LMs as initialization (next lecture)
- UNMT does not work:
 - for distant languages
 - when the source and target domain are not comparable
 - when there is insufficient monolingual corpora available for at least one of the languages

Summary

- Transformer
 - State-of-the-art NMT architecture
- Document-level NMT
 - Important for coherent translations across a document
- Unsupervised NMT
 - Important for enabling translation across a wide range of language pairs

Thank you for your attention

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